



# **Survey on FPGA Based Space Vector PWM Motion Control**

K.R.Rekha<sup>1</sup>, Shalini Vashishtha<sup>2</sup>

Professor, Dept. of ECE, SJBIT, Bangalore, Karnataka, India<sup>1</sup>

Assistant Professor, Dept. of ECE, Atria IT, Bangalore, Karnataka, India<sup>2</sup>

**ABSTRACT:** The Space vector Pulse Width Modulation (SVPWM) is possibly one of the best techniques among all the PWM techniques for variable voltage variable frequency drives. This is a direct digital technique and space vector concept is utilized to calculate the duty cycles of inverter switching devices. Rapid growth in VLSI technology and EDA techniques has given way for the development of complex and compact controllers for industrial control systems. Specific hardware technologies such as FPGAs based architecture platforms provide rapid prototyping, high performance signal processing and flexibility for implementation of drive, motion and activation control of drives. This paper reviews some of the FPGA based SVPWM motor control systems available in the literature.

**KEYWORDS:** space vector pulse width modulation, variable voltage variable frequency drives, revolving voltage vector, base vectors, sectors, digital implementation, three phase voltage source inverter, FPGA based controllers

## **I. INTRODUCTION TO SVPWM**

The Space Vector Pulse Width Modulation (SVPWM) method is an advanced PWM method and it is possibly one of the best among all the PWM techniques for variable frequency, variable voltage drives applications. In recent years, this method has gradually obtained widespread applications in power electronics and electrical drives, because of its superior performance characteristics. Compared to Sinusoidal Pulse Width Modulation (SPWM), SVPWM is more suitable for digital implementation. It is a sophisticated averaging algorithm which increases the obtainable DC voltage utilization ratio. A higher amount of AC side voltage is achieved with the same DC side voltage. In space vector theory three phase sine signals get transformed into a revolving vector with a constant magnitude and constant angular frequency. In Space vector PWM the revolving voltage vector is used as a voltage reference instead of modulating signals and the objective is to generate PWM load line voltages that are in an average equal to the given reference load voltage.

SVPWM technique attains this objective by switching the power semiconductor devices in a special sequence for example in a three phase voltage source inverter having six power semiconductor devices, the inverter can move through eight switching states. The switching states are determined by simple formulae that are easy to implement digitally. When employing a three phase inverter bridge, the phasor must be obtained by a combination of eight possible states. In order not to short-circuit the power supply, the high-side and low-side switches in any inverter leg cannot be closed at the same time. This allows 8 possible combinations of the switch states. A combination is fully described by the high-side switch states, as the low-side corresponding switch states will be complementary. The eight possible combinations, when represented in the  $\alpha/\beta$  plane, become eight space vectors, of which 2 are null vectors, as can be observed in Fig. 1. These base-vectors define a hexagon, and split it into 6 sectors. Main routines in SVPWM algorithm are

1. Determine reference phasor.
2. Determine duty cycles for base vectors.
3. Determine switching order of switches.
4. Generate PWM carrier and apply modulation.

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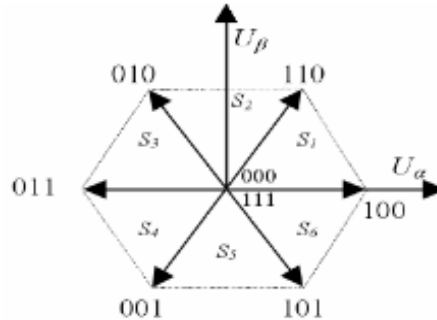


Figure 1: The base vector defined hexagon

This figure describes the eight switching states arranged in the hexagon

## Advantages of SVPWM technique

This method offers improved bus utilization, maximum output voltage is 1.155 times more than with sine triangular PWM technique. Without going into over modulation the AC output voltage can be increased. It also offers less commutation or switching losses because it offers greater flexibility to optimize switching waveforms. Only one reference space vector is needed to generate three phase sine waveforms. SVPWM switching rules give less total harmonic distortion and shifted spectrum. This method decreases the current distortion and gives low steady state torque, flux and current ripple. More advanced vector control can be implemented using SVPWM as reference voltage is a two dimensional quantity.

## II. METHODOLOGY

In this paper, section A describes a method to combine space vector and carrier based modulation and produce seven types of modulation strategies implemented on FPGA platform. Section B has a technique to reduce the computational overheads of the SVPWM algorithm by introducing an intermediate variable. Section C proposes multisampling space vectors in one switching period which results in improved performance of the voltage source inverter used in drives. Section D uses the SVPWM technique to control the servomotor system. Section E describes FPGA Based Implementation of Space Vector Modulated Direct Torque Control For Induction Motor Drives. Section F Paper focuses on the design of a low power and high performance FPGA based Digital Space Vector Pulse Width Modulation (DSVPWM) controller for three phase voltage source inverter. A new method is proposed to realize easy, accurate and high performance DSVPWM technique based on FPGA with low resource consumption and reduced execution time than conventional methods. Section G Work focuses on the design of a low power and high performance VHDL based SVPWM controller for three phase Induction Motor drives based on FPGAs.

### A. FPGA-Based SVPWM Trigger Generator for a 341 Voltage Source Inverter

Cleumar S. Moreira<sup>1</sup>, Raimundo C. S. Freire<sup>1</sup>, Elmar U. K. Melcher<sup>1</sup>, Gurdip S. Deep<sup>1</sup>, Sebastian Y. C. Catunda<sup>2</sup>, Raimundo N. C. Alves<sup>3</sup>

In this paper the architecture of a reconfigurable FPGA-based pulse width modulator for generating trigger pulses for a 3 phase voltage source inverter is presented. This circuit is based on a mixture of the space vector approach and the carrier-based modulation method. This circuit is capable of 7 different predefined modulation strategies. This architecture permits inclusion of a new user-defined strategy. The modulator structure has been decomposed into different functional modules and described in Verilog-HDL. The resulting code has been compiled and simulated for a 2000 gate FPGA. PWM trigger pulses are generated by directly comparing the reference signals against each other. In the carrier-based modulation, a zero sequence component is added to the three sinusoidal reference signals, thus distorting the reference signals to eliminating the certain harmonic components from the inverter output voltage. By comparison of this distorted reference signal with the triangular carrier, different switching patterns, are generated in accordance with chosen zero sequence component.

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## Structure of the Proposed Modulator

The **multiplier module** is used to multiply index **m** with data read from the sinusoidal module. In the **modulation module**, each of the values stored in the sinusoidal module are multiplied in the multiplier module by the 10-bit number representing the modulation index and this gives the modulation signal which is compared with the carrier signal instant by instant. To this modulating signal is then summed a zero sequence component using a finite state machine. The **delay module** has as inputs, the PWM pulses generated as a result of the comparison between the reference and carrier waveforms and identifies the positive and negative transitions. For those input signals, which suffers simultaneous transitions, a delay (dead time) is introduced to avoid simultaneous operation or conduction of switches in the same leg. In the **SVM (Space Vector Modulation) module** the calls are made to the modulation, carrier and delay modules, supervising the communication and synchronization operations. The final command pulses are then generated. The input signals to this module correspond to the flags and command pulses and the same are designed to supervise the read/write operations of the internal variables that are necessary for the configuration of the modulator. This paper presents design and implementation of a versatile FPGA based space vector modulator. This configuration is coded in Verilog HDL describing aspects of synchronism and communication between modules.

### B. An Efficient SVPWM Algorithm With Low Computational Overhead for Three-Phase Inverters Zeliang Shu, Student Member, IEEE, Jian Tang, Yuhua Guo, and Jisan Lian

This paper proposes and develops a compact algorithm of space vector pulsewidth modulation (SVPWM) for three-phase inverters. Simplified by the proposed method, the conventional SVPWM is decomposed into fast integer operations entirely by using an intermediate vector, which will properly counteract the redundant calculations of the remaining procedures. This concept can not only simplify a two-level scheme, but is also suited for multilevel implementation. Since it can be implemented without any multiplier or divider, the fast algorithm is especially suitable for field programmable gate array applications. Then, an area and speed efficient IP-core based on this algorithm is built and tested. It ensures lower hardware resource usage, and at the same time, operates several times faster than some reported examples. Experimental results obtained from a dc-ac inverter prototype are also presented to verify the viability and effectiveness of the proposed algorithm. IP-core design based on FPGA adopting the compact architecture requires much less resource and provides faster operating frequency than the conventional scheme. This concept can be used for the simplification of multilevel SVPWM scheme also. Proposed algorithm can also be used in software applications, such as DSP or micro-controller technologies, where the ability to accurately generate SVPWM pattern at real-time is crucial.

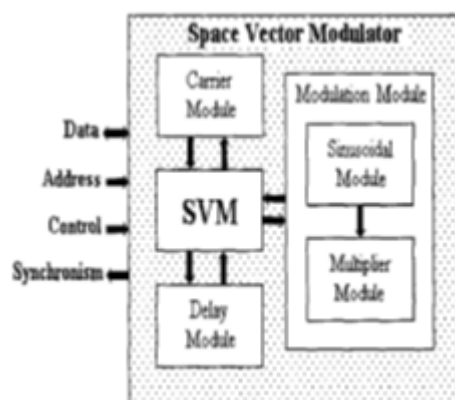


Figure 2: Structure of Proposed modulator:  
This figure describes the various modules of the proposed modulator

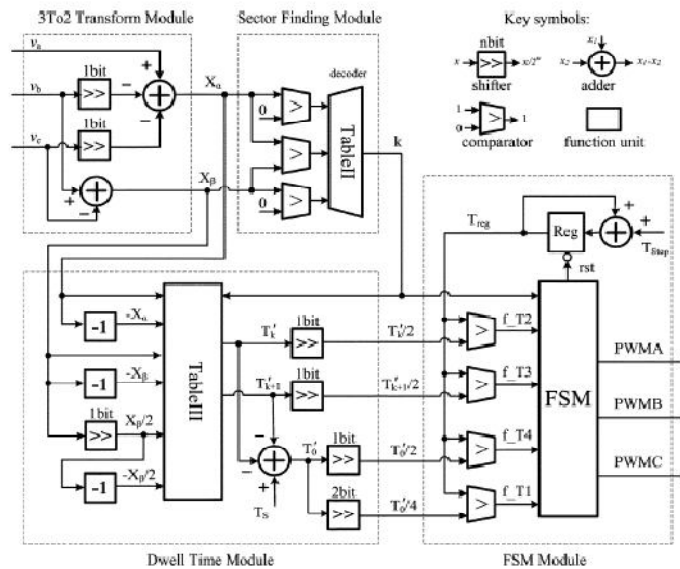


Figure 3: Compact architecture of the proposed SVPWM algorithm

### C. Three-Phase VSI with FPGA-Based Multisampled Space Vector Modulation

Giovanna Oriti, Senior Member, IEEE, and Alexander L. Julian, Member, IEEE

This paper demonstrates improved performance of a three-phase voltage source inverter (VSI) when digital multi-sampled space vector modulation is used. The modulator and the inverter controller are implemented entirely using a field-programmable gate array platform, thus achieving increased bandwidth with respect to a typical digital signal processor or microprocessor-based controller. Increased controller bandwidth results in lower output voltage harmonic distortion in the frequency range above the fundamental and below the switching frequency. Experimental validation is presented together with the analysis carried out using a state space model of a VSI with an output LC filter.

Embedding space vector modulation in an FPGA creates an opportunity to recalculate the space vector timers multiple times during one switching period. This technique is often referred to as multiple sampling of the reference signal and can be implemented only if parallel computing is possible, as is the case with FPGA-based controllers.

This paper shows that the increased controller bandwidth, resulting from multiple sampling, is very beneficial for the output voltage quality. Bode plots created from simulations were used to understand the system gain and phase margins and tune the PI controller gains. Experimental time-domain and frequency-domain waveforms have showed the improved voltage quality of the VSI output voltage when 20 samples per period are used compared to typical double update space vector modulation.

### D. Design and Implementation of SVPWM Servo Control System Based on FPGA

Pang Haiyan, Xie Yun, Xiao Shanshan, Chen Bingcheng

The SVPWM servo control system described in this paper uses Altera's Cyclone II series FPGA chips, the corresponding FPGA development software platform is Quartus II 7.2. Quartus II 7.2 development platform includes HDL code input, component symbols input and circuit design and simulation EDA software embedded and other parts, in which functional simulation and timing simulation of the entire system design stage is the crucial phase, it can identify system design problems as soon as possible.

A hardware implementation method of SVPWM is shown, which lies in the calculation of the two-axis stator voltage component, and then transforms into a three-axis from 2-axis component of modulation component (through the coordinate transformation) the output waveform is converted to the best pulse width modulated signal through the

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adjusted SVPWM converter, the modulation signal entering the latch circuit can be set for the process of adding dead delay time the final modulated waveform is then used to control the three-phase inverter circuit.

The SVPWM Servo Control System involves the calculation of pulse time and the sinusoidal signal generation, so numerical calculation and the calculation median must be taken into account. As the floating-point computational complexity is high, the system has used integer arithmetic instead, later when it is improved, it can be enhanced from 8-bit to 12-bit, 16-bit even to 32-bit. This design of servo-control system has used 8-bit integer arithmetic, the values of sine reference tables are stored in the EPROM inside the FPGA.

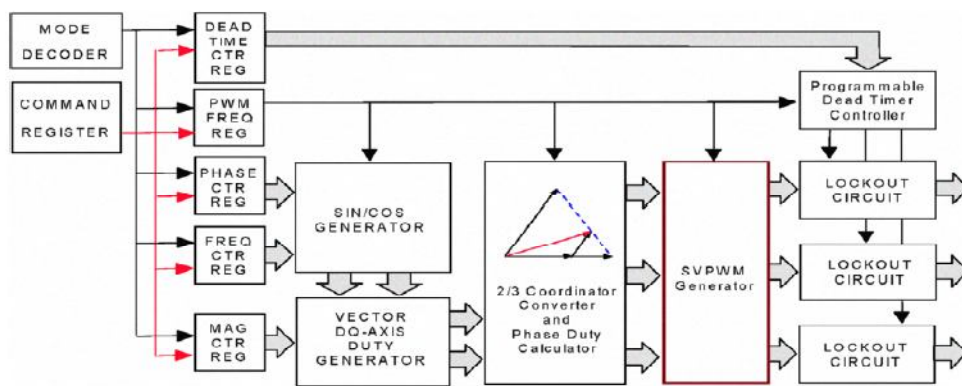


Figure 4: SVPWM digital servo Control system based FPGA  
This figure describes the design of the digital servo system based on FPGA

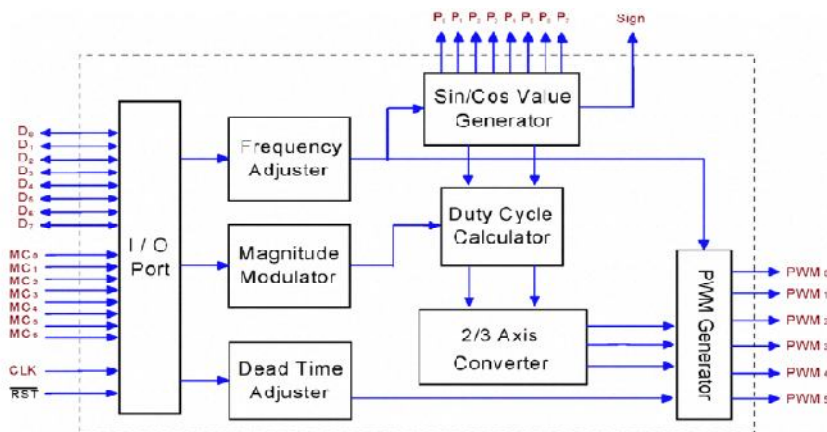


Figure 5: SVPWM control Module

This figure describes SVPWM control module that includes Frequency Adjuster, Magnitude Modulator, Dead Time Adjuster, Sin/Cos value generation, Duty Cycle Calculator, 2/3 Axis Converter

## E. FPGA Based Implementation of Space Vector Modulated Direct Torque Control For Induction Motor Drive

R. Rajendran, Senior Member IACSIT and Dr. N. Devarajan

In this paper a flexible, high computation speed and cost effective field programmable gate array (FPGA) based space vector modulated (SVM) direct torque control for an induction motor is presented. Direct Torque Control (DTC) using space vector modulation is shown to have the low steady state torque ripple, flux ripple and current distortion that is characteristic of space vector modulation and fast transient performance that is characteristic of direct torque control. This system has been implemented on the Xilinx Spartan 3E FPGA. The proposed method has the control objective of



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selecting the exact stator voltage vector that changes stator flux to meet the load angle reference and hence the desired torque while keeping flux amplitude constant. A space vector modulation algorithm is used to apply the required stator voltage vector. System is illustrated by the control system block diagram below.

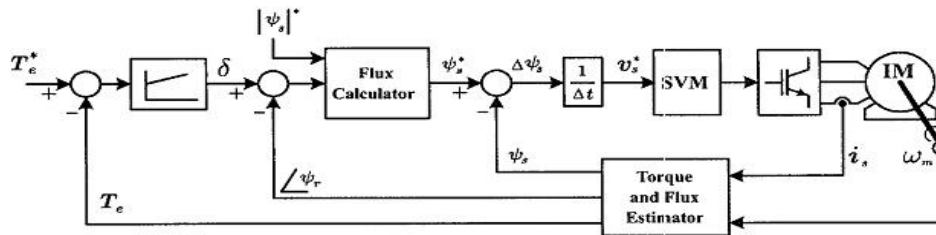


Fig 6: Direct Torque Control setup

A low cost Xilinx Spartan 3E FPGA, that contains 4,00,000 logical gates and works at 50 MHz (clock period equal to 20ns), was used as target component for the implementation of this controller. By implementing this controller in an FPGA, very good performance is reached, thanks to the inherent parallelism of FPGA-based solutions and their great flexibility to achieve different control functions.

### F. High Performance FPGA Based Digital Space Vector PWM Three Phase Voltage Source Inverter

Bahram Rashidi, Mehran Sabahi

This paper focuses on the design of a low power and high performance FPGA based Digital Space Vector Pulse Width Modulation (DSVPWM) controller for three phase voltage source inverter. A new method is proposed to realize easy, accurate and high performance DSVPWM technique based on FPGA with low resource consumption and reduced execution time than conventional methods. Equations of SVPWM are relatively complicated and need a considerable time to execute on a typical microcontroller, therefore a simple method is presented to minimize run time of instructions. Proposed digital design for sector determination implements Rules based on simple and low power logic circuits, proposed design is based on combinational logic circuits thus there is increased performance and reduced power consumption. This proposed digital circuit implements sector determination completely and accurately. For increasing performance of design sub-pipelining technique can be used. The advantages of this technique over the other literatures include flexibility, high accuracy and reduced area. Therefore a simple method has been presented to change complicated SVPWM equations to a collection of shift, add and other similar uncomplicated orders to minimize run time of instructions. Proposed method has high performance, Stress Reduction, low power and high accuracy. To verify the proposed design a laboratory prototype has been arranged using of cyclone II FPGA board, an optical interface as IGBT drivers of voltage source inverter with an induction motor output load. Laboratory experiments and Xpower analyzer results demonstrate that, because of reduced hardware usage percentage, easy and fast instructions, proposed method has better performance and less power consumption than others works. Total power consumption of controller is reduced to 37 mW at 100MHz clock frequency.

### G. FPGA Implementation of SVPWM Control Technique for Three Phase Induction Motor Drive Using Fixed Point Realization

Chaurasiya Rohit B., Mukesh D. Patil, Divya Shah 1 and Abhijit Kadam 2 Electronics Engineering Ramrao Adik Institute of Technology Nerul, Navi Mumbai

This work focuses on the design of low power and high performance VHDL based SVPWM controller for three phase Induction Motor drive on FPGAs. The integer realization of software part results in large number of subroutines thus utilizing large hardware resources on FPGA board leading to more power consumption. Also due to large code density the computational time is more. In this work the software part is implemented with proposed fixed point realization which increases the accuracy, also since there are no subroutines, it reduces total area on FPGA board. The code density is less, thereby decreasing computational time and power consumption. The simulation results for SVPWM generated signals are also given in this work. To prove the effectiveness of the proposed method the hardware utilization by the proposed method are compared with integer realization.



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It is observed that, the fixed point implementation requires less hardware, improves accuracy and makes the implementation simpler as compared to integer realization.

### III. CONCLUSION

With rapid progress in VLSI technology the development of efficient motor control systems has also made major progress. Many of the motor drives in use have DSP based digital control strategy, this has the advantage of simple software control and flexibility. However recent devices like FPGAs provide rapid prototyping, high performance signal processing and flexibility due to their reconfigurable architecture. In particular an FPGA-based SVPWM modulator can take multiple samples of the reference voltage and recalculate the power converter switching states and timers several times over one switching period which is an advantage over DSP based controllers. However, in many cases, the design of FPGA-based controller architectures is rather intuitive and requires the designer to master different areas (micro-electronics, control, and electrical machine theories). It is particularly true for complex algorithm structures such as the ones found in drive control applications. This paper makes an attempt to survey the techniques present in the literature for FPGA based space vector modulated motor control systems.

### FUTURE SCOPE

The FPGA based design of SVPWM can be extended for low Power realization, and also to improve power speed product of FPGAs. This discussion also lays the foundation of analyzing motor control systems based on SOC (system on chip) specialization for the future.

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